Linear Regression

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Outline

- The Model
- Estimation
 - Ordinary Least Square
 - Method of Moments
 - Maximum Likelihood Estimation
- Properties of OLS Estimator
 - Unbiasedness
 - Consistency
 - Efficiency

What is linear regression?

- We want to explain an economic variable y using x, which is usually a vector.
- For example, y may be the wage of an individual, and x include factors such as experience, education, gender, and so on.
- Let $x = (1, x_1, ..., x_k)$, and let its realization for *i*th-individual be $x_i = (1, x_{i1}, ..., x_{ik})'$, we may write:

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u. \tag{1}$$

Some Terminologies

Now we have

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u.$$
(2)

- y is called the "dependent variable", the "explained variable", or the "regressand"
- The elements in x are called the "independent variables", "explanatory variables", "covariates", or the "regressors".
- β's are coefficients. In particular, β₀ is usually called "intercept parameter" or simply called "constant term", and (β_j, 1 ≤ j ≤ k) are usually called slope parameters.
- ► u is called the "error term", "residuals", or disturbances and represents factors other than x that affect y.

An Example

• We may have an econometric model of wages:

$$wage_i = \beta_0 + \beta_1 edu_i + \beta_2 expr_i + u_i$$

- edui denotes the education level of individual i in terms of years of schooling and expri denotes the working experience of individual i.
- β₀ is the constant term or the intercept. It measures what a male worker would expect to get if he has zero education and zero experience.
- β₁ is the slope parameter for the explanatory variable *edu*. It measure the marginal increase in wage if a worker gains additional year of schooling, holding other factors fixed, or controlling for other factors.
- u_i may include the gender, the luck, or the family background of the individual, etc.

Partial Effects

- $(\beta_j, j = 1, .., k)$ can be interpreted as "partial effects".
- For example, for the wage equation, we have

$$\Delta wage = \beta_1 \Delta edu + \beta_2 \Delta expr + \Delta u.$$

If we hold all factors other than edu fixed, then

$$\Delta wage = \beta_1 \Delta edu.$$

- So β_1 is the partial effect of education on wage.
- We say: With one unit of increase in *edu*, an individual's wage increases by β₁, holding other factors fixed, or controlling for other factors.

Econometric Clear Thinking

- Whenever we make comparisons or inferences, we should hold relevant factors fixed.
- This is achieved in econometrics by multiple linear regression.
- The partial effects interpretation is not without problem. It is partial equilibrium analysis.
- We may have the socalled "general equilibrium problem", which happens when a change in a variable leads to changes in the structure of regression equation.
- In most cases, however, partial effects analysis is a good approximation, or, the best alternative.

Classical Linear Regression Assumptions

- (1) Linearity
- (2) Random sampling $-\rightarrow (x_i, y_i)$ are iid across i
- (3) No perfect collinearity ⇔ Any element in x cannot be represented by the linear combination of other elements.
- (4) Zero conditional mean \Leftrightarrow

$$\mathbb{E}(u|x) = \mathbb{E}(u|x_1, x_2, ..., x_k) = 0.$$

(5) Homoscedasticity

 $\operatorname{var}(u|x) = \sigma^2.$

(6) Normality

$$u|x \sim N(0, \sigma^2).$$

More on Linearity

- Linearity can be achieved by transformation.
- For example, we may have

 $\log(wage_i) = \beta_0 + \beta_1 \log(exper_i) + \beta_2 \log(educ_i) + \beta_3 female_i + u_i.$

Now the parameter β₁ represents the elasticity of wage with respect to changes in experiences:

 $\beta_1 = \frac{\partial \log(wage_i)}{\partial \log(exper_i)} = \frac{\partial wage_i/wage_i}{\partial exper_i/exper_i} \approx \frac{\Delta wage_i/wage_i}{\Delta exper_i/exper_i}.$

More on No Perfect Collinearity

True or False?

(1) "No Perfect Collinearity" does not allow correlation. For example, the following is perfect collinearity:

testscore = $\beta_0 + \beta_1 eduExpend + \beta_2 familyIncome + u$.

(2) The following model suffers from perfect collinearity:

$$cons = \beta_0 + \beta_1 income + \beta_2 income^2 + u.$$

(3) The following model suffers from perfect collinearity:

 $\log(cons) = \beta_0 + \beta_1 \log(income) + \beta_2 \log(income^2) + u.$

(4) The following model suffers from perfect collinearity:

 $cons = \beta_0 + \beta_1 husblncome + \beta_2 wifelncome + \beta_3 family lncome + u.$

More on Zero Conditional Mean

- If $\mathbb{E}(u|x) = 0$, we call x "exogenous".
- If $\mathbb{E}(u|x) \neq 0$, we call x "endogenous".
- The notion of being "exogenous" or "endogenous" can be understood in the following model,

$$L = \alpha W + \gamma X + u,$$

where both the employment level (L) and the average wage (W) are endogenous variables, while the foreign exchange rate (X) can be considered exogenous. The residual u should contain shocks from both supply and demand sides.

Endogenous Wage

If the employment level and the average wage are determined by

$$L_s = bW + v_s$$

$$L_d = aW + cX + v_d$$

$$L_d = L_s,$$

Then we can solve for the equilibrium employment and wage rate:

$$W = \frac{c}{b-a}X - \frac{v_s - v_d}{b-a}$$
$$L = \frac{bc}{b-a}X - \frac{av_s - bv_d}{b-a}$$

It is obvious that $cov(W, v_d) \neq 0$ and $cov(W, v_s) \neq 0$. Thus W should be correlated with u, hence the endogeneity in econometric sense.

More on Zero Conditional Mean

- In econometrics, we call an explanatory variable x "endogenous" as long as E(u|x) ≠ 0.
- Usually, nonzero conditional mean is due to
 - Endogeneity
 - Missing variables (e.g., ability in wage equation)
 - Wrong functional form (e.g., missing quadratic term)

More on Homoscedasticity

- If var(u_i|x_i) = σ², we call the model "homoscedastic". If not, we call it "heteroscedastic".
- ► Note that var(u_i|x_i) = var(y_i|x_i). If var(y_i|x_i) is a function of some regressor, then there would be heteroscedasticity.
- Examples of heteroscedasticity
 - Income v.s. Expenditure on meals
 - Gender v.s. Wage
 - •

Ordinary Least Square

We have

$$y_i = \beta_0 + \beta_1 x_{i1} + \cdots + \beta_k x_{ik} + u_i.$$

The OLS method is to find *beta*'s such that the sum of squared residuals (SSR) is minimized:

$$SSR(\beta_0, ..., \beta_k) = \sum_{i=1}^{n} [(y_i - (\beta_0 + \beta_1 x_{i1} + \dots + \beta_k x_{ik})]^2.$$

• OLS minimizes *a* measure of fitting error.

First Order Conditions of OLS

To minimize SSR, we find the first-order conditions of the minimization problem:

$$\frac{\partial \text{SSR}}{\partial \beta_0} = 0$$
$$\frac{\partial \text{SSR}}{\partial \beta_1} = 0$$
$$\vdots$$
$$\frac{\partial \text{SSR}}{\partial \beta_k} = 0$$

First Order Conditions of OLS

We obtain:

$$2\sum_{i=1}^{n} ((y_{i} - (\hat{\beta}_{0} + \hat{\beta}_{1}x_{i1} + \dots + \hat{\beta}_{k}x_{ik})) = 0$$

$$2\sum_{i=1}^{n} ((y_{i} - (\hat{\beta}_{0} + \hat{\beta}_{1}x_{i1} + \dots + \hat{\beta}_{k}x_{ik}))x_{i1} = 0$$

$$\vdots$$

$$2\sum_{i=1}^{n} ((y_{i} - (\hat{\beta}_{0} + \hat{\beta}_{1}x_{i1} + \dots + \hat{\beta}_{k}x_{ik}))x_{ik} = 0.$$

We have (1 + k) equations for (1 + k) unknowns. If there is no perfect collinearity, we can solve for these equations.

OLS for Naive Regression

We may have the following model

$$y_i = \beta x_i + u.$$

Then the first-order condition is:

$$\sum_{i=1}^n (y_i - \hat{\beta} x_i) x_i = 0$$

We obtain

$$\hat{\beta} = \frac{\sum_{i=1}^{n} y_i x_i}{\sum_{i=1}^{n} x_i^2}$$

OLS for Simple Regression

The following is called a "simple regression":

$$y_i = \beta_0 + \beta_1 x_i + u_i.$$

Then the first-order conditions are:

$$\sum_{i=1}^{n} (y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i)) = 0$$
$$\sum_{i=1}^{n} (y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i)) x_i = 0$$

OLS for Simple Regression, Continued

From the first-order conditions, we obtain

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (y_i - \bar{y})(x_i - \bar{x})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

and $\hat{\beta}_0 = \bar{y} - \bar{x}\hat{\beta}_1$, where $\bar{x} = 1/n\sum_{i=1}^n x_i$ and $\bar{y} = 1/n\sum_{i=1}^n y_i$.

More on OLS for Simple Regression

From $y = \beta_0 + \beta_1 x + u$, we have

$$\beta_1 = \frac{\operatorname{cov}(x, y)}{\operatorname{var}(x)}.$$

And we have obtained

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (y_i - \bar{y})(x_i - \bar{x})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{\frac{1}{n} \sum_{i=1}^n (y_i - \bar{y})(x_i - \bar{x})}{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2} = \frac{\hat{\operatorname{cov}}(x, y)}{\hat{\operatorname{var}}(x)}$$

Hence β_1 measures the correlation between y and x.

In the simple regression model,

$$y=\beta_0+\beta_1x+u.$$

- β_0 is the mean of y
- β_1 is the correlation coefficient between x and y

Estimated Residual

Let

$$\hat{u}_i = y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i).$$

From the first-order conditions we have

$$\bar{\hat{u}}=\frac{1}{n}\sum_{i=1}^{n}\hat{u}_{i}=0,$$

and

$$\frac{1}{n}\sum_{i=1}^n x_i\hat{u}_i=0.$$

Connection between Simple and Naive

We have

$$\begin{cases} y_i = \hat{\beta}_0 + \hat{\beta}_1 x_i + \hat{u}_i \\ \bar{y} = \hat{\beta}_0 + \hat{\beta}_1 \bar{x} + 0. \end{cases}$$

Hence

$$y_i - \bar{y} = \hat{\beta}_1(x_i - \bar{x}) + \hat{u}_i.$$

Using the formula for the naive regression, we obtain:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (y_i - \bar{y})(x_i - \bar{x})}{\sum_{i=1}^n (x_i - \bar{x})^2}.$$

Regression Line

For the simple regression model,

$$y=\beta_0+\beta_1x+u.$$

We can define a "regression line":

$$y = \hat{\beta}_0 + \hat{\beta}_1 x.$$

It is easy to show that

$$\bar{y} = \hat{\beta}_0 + \hat{\beta}_1 \bar{x}.$$

In Matrix Language

- For models with two or more regressors, the expression for $\hat{\beta}_i$ are very complicated.
- However, we can use matrix language to obtain more beautiful and more memorable expressions. Let

$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, X = \begin{pmatrix} 1 & x_{11} & \cdots & x_{1k} \\ 1 & x_{21} & \cdots & x_{2k} \\ \vdots & & \vdots \\ 1 & x_{n1} & \cdots & x_{nk} \end{pmatrix}, \beta = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{pmatrix}, u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$

Then we may write the multiple regression as

$$Y = X\beta + u.$$

Some Special Vectors and Matrices

▶ Vector of ones, ι = (1, 1, ..., 1)'. For a vector of the same length, we have

$$\sum_{i=1}^n x_i = x'\iota = \iota'x, \quad \text{and} \quad \frac{1}{n}\sum_{i=1}^n x_i = (\iota'\iota)^{-1}\iota'x.$$

- Identity matrix, I.
- Projection matrix, square matrices that satisfy $P^2 = P$.
 - If P is symmetric, it is called an orthogonal projection (e.g., $P = X(X'X)^{-1}X'$)
 - Oblique projection, e.g., $P = X(W'X)^{-1}W'$, $P = \begin{bmatrix} 0 & 0 \\ \alpha & 1 \end{bmatrix}$.
- If P is an orthogonal projection, so is I P.

Range of Matrix

- The span of a set of vectors is the set of all linear combinations of the vectors.
- ► The range of a matrix X, R(X), is the span of the columns of X.
- ▶ $\mathcal{R}(X)^{\perp}$ is the orthogonal complement $\mathcal{R}(X)$, which contains all vectors that is orthogonal to $\mathcal{R}(X)$.
 - Two vectors, x and y, are orthogonal if $x \cdot y = x'y = 0$.
 - A vector y is orthogonal to a subspace U if for all x ∈ U, x ⋅ y = 0.
 R ([1 0]) is the x-axis.

Orthogonal Projection on $\mathcal{R}(X)$

By definition, the orthogonal projection of y on R(X) can be represented by Xβ, where β is a vector. We denote

$$\operatorname{proj}(y|X) \equiv P_X y = X\beta.$$

• $y - X\beta$ should be orthogonal to every element in $\mathcal{R}(X)$, which include every column of X. Then we may solve

$$X'(y-X\beta)=0$$

and obtain $\beta = (X'X)^{-1}X'y$. Hence $P_X = X(X'X)^{-1}X'$ is the orthogonal projection on $\mathcal{R}(X)$.

I − P_X is the orthogonal projection on R(X)[⊥], or equivalently, N(X').

Vector Differentiation

Let z = (z₁,..., z_k) be a vector of variables and f(z) be a function of z. Then

$$\frac{\partial f}{\partial z} = \begin{pmatrix} \frac{\partial f}{\partial z_1} \\ \frac{\partial f}{\partial z_2} \\ \vdots \\ \frac{\partial f}{\partial z_k} \end{pmatrix}$$

•

Vector Differentiation

▶ In particular, if f(z) = a'z, where *a* is a vector of constants. Then

$$rac{\partial}{\partial z}(a'z)=a=rac{\partial}{\partial z}(z'a)$$

If f(z) = Az is a vector-valued function, where A is a matrix, then

$$\frac{\partial}{\partial z}(Az)=A'.$$

Vector Differentiation of Quadratic Form

If f(z) = z'Az, where A is a matrix, then

$$\frac{\partial}{\partial z}(z'Az)=(A+A')z.$$

If A is symmetric, ie, A = A', then

$$\frac{\partial}{\partial z}(z'Az) = 2Az.$$

In particular, when A = I, the identity matrix, then

$$\frac{\partial}{\partial z}(z'z)=2z$$

OLS in Matrix

The least square problem can be written as

$$\min_{\beta}(Y-X\beta)'(Y-X\beta).$$

The first-order condition in matrix form:

$$2X'(Y-X\hat{\beta})=0.$$

• Solving for β ,

$$\hat{\beta} = (X'X)^{-1}X'Y.$$

- ► The matrix of X'X is invertible since we rule out perfect collinearity.
- $X\hat{\beta}$ is nothing but the orthogonal projection of Y on $\mathcal{R}(X)$.
- If there is only one regressor and there is no constant term, X is a vector. Then the above expression reduces to the naive linear regression estimator.

An Equivalent Derivation

The least square problem can be written as

$$\min_{\beta}\sum_{i=1}^{n}(y_i-x_i^{\prime}\beta)^2,$$

where
$$x_i = (1, x_{i1}, ..., x_{ik})$$
 and $\beta = (\beta_0, \beta_1, ..., \beta_k)$.

The first-order condition in matrix form:

$$\sum_{i=1}^n 2x_i(y_i - x_i'\hat{\beta}) = 0.$$

Solving for β,

$$\hat{\beta} = \left(\sum_{i=1}^n x_i x_i'\right)^{-1} \left(\sum_{i=1}^n x_i y_i\right).$$

Equivalence

We can check that

$$X'X = \sum_{i=1}^{n} x_i x'_i$$
, and $X'Y = \sum_{i=1}^{n} x_i y_i$.

If there is only one regressor and there is no constant term, x_i is a scalar. Then the above expression reduces to the naive linear regression estimator.

The Population Moments

From the assumption $\mathbb{E}(u|x) = 0$, we have

$$\mathbb{E}(u) = 0$$
, and $\mathbb{E}(ux_j) = 0, j = 1, ..., k$.

This is

$$\begin{cases} \mathbb{E}(y - (\beta_0 + \beta_1 x_1 + \dots + \beta_k x_k)) = 0\\ \mathbb{E}((y - (\beta_0 + \beta_1 x_1 + \dots + \beta_k x_k))x_1) = 0\\ \vdots\\ \mathbb{E}((y - (\beta_0 + \beta_1 x_1 + \dots + \beta_k x_k))x_k) = 0 \end{cases}$$

The above equations are called "moment conditions".

The Sample Moments

We can estimate population moments by sample moments. For example, the sample moment of $\mathbb{E}(u)$ is

$$\frac{1}{n}\sum_{i=1}^{n}u_{i}=\frac{1}{n}\sum_{i=1}^{n}(y_{i}-(\beta_{0}+\beta_{1}x_{i1}+\cdots+\beta_{k}x_{ik})).$$

Similarly, the sample counterpart of $\mathbb{E}(ux_j) = 0$ is

$$\frac{1}{n}\sum_{i=1}^{n}u_{i}x_{ij}=\frac{1}{n}\sum_{i=1}^{n}(y_{i}-(\beta_{0}+\beta_{1}x_{i1}+\cdots+\beta_{k}x_{ik}))x_{ij}=0.$$

Method of Moments (MM)

Plug the sample moments into the moment conditions, we obtain

$$\frac{1}{n}\sum_{i=1}^{n}(y_{i}-(\hat{\beta}_{0}+\hat{\beta}_{1}x_{i1}+\cdots+\hat{\beta}_{k}x_{ik}))=0,$$

and

$$\frac{1}{n}\sum_{i=1}^{n}(y_{i}-(\hat{\beta}_{0}+\hat{\beta}_{1}x_{i1}+\cdots+\hat{\beta}_{k}x_{ik}))x_{ij}=0, j=1,...,k.$$

We can see that these equations are the same as those in the first-order conditions of the OLS.

The Distribution Assumption

 Under CLR Assumption (6), *u* is normally distributed with mean 0 and variance σ². The density function of *u* is given by

$$p(u;\sigma) = rac{1}{\sqrt{2\pi\sigma}} \exp\left(-rac{u^2}{2\sigma^2}
ight).$$

- Then we can estimate the linear regression model using MLE.
- More generally, we can assume other distributional function for u, t-distribution for example.

Likelihood Function

► By the Assumption (2), random sampling, the joint distribution of (u₁,..., u_n) is

$$p(u_1,...,u_n;\theta)=p(u_1;\theta)p(u_2;\theta)\cdots p(u_n;\theta).$$

 Given observations (Y, X), the likelihood function is defined as

$$p(\beta, \theta|y, X) = p(y_1 - x'_1\beta, ..., y_n - x'_n\beta; \theta)$$

= $p(y_1 - x'_1\beta; \theta)p(y_2 - x_2\beta; \theta) \cdots p(y_n - x'_n\beta; \theta)$

Maximum Likelihood Estimation

- MLE implicitly assumes that what happens should most likely happen.
- ▶ MLE is to solve for $\hat{\beta}$ and $\hat{\theta}$ such that the likelihood function is maximized,

$$\max_{\beta,\theta} p(\beta,\theta|y,X).$$

In practice, we usually maximize the log likelihood function:

$$\log(p(\beta, \theta|y, X)) = \sum_{i=1}^{n} \log(p(y_i - x'_i\beta; \theta)).$$

MLE of Classical Linear Regression

- We assume $u_i \sim \text{iid } N(0, \sigma^2)$.
- The log likelihood function is

$$\log(p(\beta,\sigma|y,X)) = -\frac{n}{2}\log(2\pi) - n\log(\sigma) - \frac{1}{2\sigma^2}\sum_{i=1}^{n}(y_i - x_i'\beta)^2.$$

 \blacktriangleright The first-order condition for β is

$$\sum_{i=1}^n x_i(y_i - x'_i\hat{\beta}) = 0.$$

• This yields the same $\hat{\beta}$ as in OLS.

Definition

• We call an estimator $\hat{\beta}$ is unbiased if

$$\mathbb{E}\hat{\beta} = \beta.$$

- *β̂* is a random variable. For example, the OLS estimator
 β̂ = (X'X)⁻¹X'Y is random since both X and Y are sampled
 from a population.
- Given a sample, however, β̂ is determined. So unbiasedness is NOT a measure of how good a particular estimate is, but a property of a good procedure.

The Unbiasedness of OLS Estimator

Theorem: Under Assumptions (1) through (4), we have

$$\mathbb{E}(\hat{\beta}_j) = \beta_j, \ j = 0, 1, ..., k.$$

Proof:

$$\mathbb{E}(\hat{\beta}) = \mathbb{E}(X'X)^{-1}X'Y = \mathbb{E}(X'X)^{-1}X'(X\beta + U) = \beta + \mathbb{E}(X'X)^{-1}X'U = \beta.$$

Omitted Variable Bias

- When we, mistakenly or due to lack of data, exclude one or more relevant variables, OLS yields biased estimates. This bias is called "omitted variable bias".
- For example, suppose the wage of a worker is determined by both his education and his innate ability:

wage =
$$\beta_0 + \beta_1$$
 education + β_2 ability + u .

The ability, however, is not observable. We may have to estimate the following model,

wage =
$$\beta_0 + \beta_1$$
 education + v ,

where $v = \beta_2 a bill ty + u$.

The General Case

Suppose the true model, in matrix form, is

$$Y = X_1\beta_1 + X_2\beta_2 + U, \tag{3}$$

where β_1 is the parameter of interest. However, we omit X_2 and estimate

$$Y = X_1 \beta_1 + V. \tag{4}$$

Denote the OLS estimator of β_1 in (3) as $\hat{\beta}_1$ and the OLS estimator of β_1 in (4) as $\tilde{\beta}_1$. Then

$$\mathbb{E}(\tilde{\beta}_1|X_1,X_2) = \beta_1 + (X_1'X_1)^{-1}X_1'X_2\beta_2.$$

Formula of Omitted-Variable Bias

Suppose we only omit one relevant variable, ie, X_2 is a vector. Then $(X'_1X_1)^{-1}X'_1X_2$ is the OLS estimator of the following regression:

$$X_2 = X_1 \delta + W.$$

So we have

$$\mathbb{E}(\tilde{\beta}_1|X_1,X_2) = \beta_1 + \hat{\delta}\beta_2.$$

A Special Case

Suppose the true model is

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + u.$$

But we estimated

$$y = \tilde{\beta}_0 + \tilde{\beta}_1 x_1 + \tilde{\nu}.$$

From the formula of omitted-variable bias,

$$\mathbb{E}(\tilde{\beta}_1|x_1,x_2) = \beta_1 + \hat{\delta}_1\beta_2,$$

where $\hat{\delta}_1$ is the OLS estimate of δ_1 in

$$x_2 = \delta_0 + \delta_1 x_1 + w.$$

Bias Up or Down?

We have

$$\mathbb{E}(\tilde{\beta}_1|x_1,x_2) = \beta_1 + \hat{\delta}_1\beta_2.$$

Recall that δ_1 measures the correlation between x_1 and x_2 . Hence we have

| OLS Bias | $\operatorname{corr}(x_1, x_2) > 0$ | $\operatorname{corr}(x_1, x_2) < 0$ |
|---------------|-------------------------------------|-------------------------------------|
| $\beta_2 > 0$ | | |
| $\beta_2 < 0$ | | |

Return to Education

Back to our example, suppose the wage of a worker is determined by both his education and his innate ability:

wage =
$$\beta_0 + \beta_1$$
 education + β_2 ability + u .

The ability, however, is not observable. We may have to estimate the following model,

wage =
$$\beta_0 + \beta_1$$
 education + v ,

where $v = \beta_2 abililty + u$.

Are we going to overestimate or underestimate the return to education?

Definition

• We say $\hat{\beta}$ is consistent if

$$\hat{\beta} \to \beta$$
 as $n \to \infty$.

This basically says, if we observe more and more, we can estimate our model more and more accurately till exactness.

Law of Large Number

Let $x_1, x_2, ..., x_n$ be iid random variables with mean μ . Then

$$\frac{1}{n}\sum_{i=1}^n x_i \to_p \mu.$$

LLN for Vectors and Matrices

▶ The x_i in LLN can be vectors. And if

$$\mathbb{E}x = \mathbb{E}\begin{pmatrix} x_{i,1} \\ x_{i,2} \\ \vdots \\ x_{i,k} \end{pmatrix} = \mu = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_k \end{pmatrix},$$

then

$$\frac{1}{n}\sum_{i=1}^n x_i \to_p \mu.$$

• The same is also true for matrices.

Consistency of OLS Estimator

We have $\hat{\beta} = \beta + \left(\frac{1}{n}\sum_{i=1}^{n}x_{i}x_{i}'\right)^{-1}\left(\frac{1}{n}\sum_{i=1}^{n}x_{i}u_{i}\right).$ If $\mathbb{E}x_{i}x_{i}' = Q$, and $\mathbb{E}x_{i}u_{i} = 0$, then by LLN we have $\hat{\beta} \rightarrow_{p} \beta.$

Inconsistency of OLS Estimator

When $\mathbb{E}x_i u_i = \Delta \neq 0$, then

$$\hat{\beta} \rightarrow_{p} \beta + Q\Delta.$$

- Inconsistency occurs when x_i is correlated with u_i, or, x is "endogenous".
- $Q\Delta$ is called "asymptotic bias".

Relative Efficiency

- ▶ If $\hat{\theta}$ and $\tilde{\theta}$ are two unbiased estimators of θ , $\hat{\theta}$ is efficient relative to $\tilde{\theta}$ if $var(\hat{\theta}) \leq var(\tilde{\theta})$ for all θ , with strict inequality for at least one θ .
- Relative efficiency compares preciseness of estimators.
- ► Example: Suppose we want to estimate the population mean µ of an i.i.d. sample {x_i, i = 1,..., n}. Both x̄ and x₁ are unbiased estimators, however, x̄ is more efficient since var (x̄) = var(x₁)/n ≤ var(x₁).
- If θ is a vector, we compare the covariance matrices of $\hat{\theta}$ and $\tilde{\theta}$ in the sense of positive definiteness.

Covariance Matrix of A Random Vector

The variance of a scalar random variable x is

$$\operatorname{var}(x) = \mathbb{E}(x - \mathbb{E}x)^2.$$

If x is a vector with two elements,

$$\mathbf{x} = \left(egin{array}{c} x_1 \ x_2 \end{array}
ight),$$

then the variance of x is a 2-by-2 matrix (we call "covariance matrix"):

$$\Sigma_x = \left(egin{array}{c} \operatorname{var}(x_1) & \operatorname{cov}(x_1, x_2) \ \operatorname{cov}(x_2, x_1) & \operatorname{var}(x_2) \end{array}
ight),$$

where $cov(x_1, x_2)$ is the covariance between x_1 and x_2 :

$$\operatorname{cov}(x_1, x_2) = \mathbb{E}(x_1 - \mathbb{E}x_1)(x_2 - \mathbb{E}x_2).$$

Covariance Matrix of A Random Vector

More generally, if x is a vector with n elements,

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix},$$

then the covariance matrix of x is a n-by-n matrix:

$$\Sigma_x = \begin{pmatrix} \operatorname{var}(x_1) & \operatorname{cov}(x_1, x_2) & \cdots & \operatorname{cov}(x_1, x_n) \\ \operatorname{cov}(x_2, x_1) & \operatorname{var}(x_2) & \cdots & \operatorname{cov}(x_2, x_n) \\ \vdots & \vdots & & \vdots \\ \operatorname{cov}(x_n, x_1) & \operatorname{cov}(x_n, x_2) & \cdots & \operatorname{var}(x_n) \end{pmatrix}$$

Covariance Matrix of A Random Vector

The covariance matrix is the second moment of a random vector:

$$\Sigma_x = \mathbb{E}(x - \mathbb{E}x)(x - \mathbb{E}x)'.$$

• It is obvious that Σ_x is a symmetric matrix.

The Formula of Covariance Matrix

Given random vectors x and y, if

$$y = Ax$$
,

where A is a matrix. Then

$$\Sigma_y = A \Sigma_x A'.$$

Covariance Matrix of the Residual

Write the original linear regression model as

$$y_i = x_i'\beta + u_i,$$

where

$$\begin{array}{rcl} x_i & = & (1, x_{i1}, ..., x_{ik})' \\ \beta & = & (\beta_0, \beta_1, ..., \beta_k). \end{array}$$

Eu_i = 0 ⇐ Assumption (4) zero conditional mean
Eu_i² = σ² ⇐ Assumption (5) homoscedasticity
Eu_iu_j = 0 for i ≠ j ⇐ Assumption (2) random sampling
What is the covariance matrix for U = (u₁, u₂, ..., u_n)'?

Covariance Matrix of the OLS Estimator

• The covariance matrix for
$$U = (u_1, u_2, ..., u_n)'$$
 is

$$\Sigma_u = \sigma^2 I$$
,

where I is the identity matrix.

We have

$$\hat{\beta} = \beta + (X'X)^{-1}X'U.$$

• The covariance matrix of $\hat{\beta}$ is then

$$\Sigma_{\hat{\beta}} = \sigma^2 (X'X)^{-1}.$$

- The diagonal elements of Σ_{β̂} give the standard error of β̂.
- If β̃ is another unbiased estimator of β with covariance matrix Σ_{β̃}, we say β̂ is more efficient relative to β̃ if Σ_{β̃} − Σ_{β̂} is semi-positive definite for all β, with strict positive definiteness for at least one β.

Simple Regression

For a simple regression,

$$y=\beta_0+\beta_1x+u.$$

We can obtain

$$\Sigma = \frac{\sigma^2}{n\sum_i (x_i - \bar{x})^2} \left(\begin{array}{cc} \sum_i x_i^2 & -\sum_i x_i \\ -\sum_i x_i & n \end{array} \right).$$

• The variance of $\hat{\beta}_1$ is

$$\operatorname{var}(\hat{\beta}_1) = \frac{\sigma^2}{\sum_i (x_i - \bar{x})^2}.$$

- The less σ^2 , the more accurate $\hat{\beta}_1$ is.
- The more variation in x, the more accurate $\hat{\beta}_1$ is.
- And the more sample size, the more accurate $\hat{\beta}_1$ is.

Is OLS A Good Estimator?

Define what is "good":

- Is it unbiased?
- Is it consistent?
- Does it have a small variance?

Gauss-Markov Theorem

Theorem: Under Assumption 1-5, OLS is BLUE (Best Linear Unbiased Estimator).

- Define "best": smallest variance.
- Define "linear":

$$\tilde{\beta}_j = \sum_{i=1}^n w_{ij} y_i.$$
(5)

- And unbiasedness: $\mathbb{E}\tilde{\beta} = \beta$.
- The message:

We need not look for alternatives that are unbiased and are in the form of (5).

Time Series Regression Assumptions

(1) Linearity

$$y_t = \beta_0 + \beta_1 x_{1t} + \cdots + \beta_k x_{kt} + u_t.$$

(2) (x_t, y_t) are jointly stationary and ergodic.

(3) No perfect collinearity.

(4) Past and contemporary exogeneity \Leftrightarrow

 $\mathbb{E}(u_t|x_t,x_{t-1},\ldots)=0.$

Stationarity

Weak stationarity.

$$\mathbb{E}x_t = \mu$$
, $\operatorname{cov}(x_t, x_{t-\tau}) = \gamma_{\tau}$, $\tau = \dots, -2, -1, 0, 1, 2, \dots$

Strict stationarity.

$$F(X_t, ..., X_T) = F(X_{t+\tau}, ..., X_{T+\tau}),$$

where F is the joint distribution function.

Ergodicity

- ► An ergodic time series (x_t) has the property that x_t and x_{t-k} are independent if k is large.
- If (x_t) is stationary and ergodic, then a law of large number holds,

$$rac{1}{n}\sum_{t=1}^n x_t o \mathbb{E} x$$
 a.s. .

Exogeneity in Time Series Context

Strict exogeneity.

$$\mathbb{E}(u_t|X) = \mathbb{E}(u_t|...,x_{t+1},x_t,x_{t-1},...) = 0.$$

Past and Contemporary exogeneity.

$$\mathbb{E}(u_t|x_t,x_{t-1},\ldots)=0.$$

Under the Time Series Regression Assumptions (1)-(4), the OLS estimator of the time series regression is consistent.

Special Cases

Autoregressive models (AR),

$$y_t = \beta_0 + \beta_1 y_{t-1} + \cdots + \beta_p y_{t-p} + u_t.$$

Autoregressive distributed lag models (ARDL)

$$y_t = \beta_0 + \beta_1 y_{t-1} + \dots + \beta_p y_{t-p} + \gamma_1 x_{t-1} + \dots + \gamma_q x_{t-q} + u_t.$$

Autoregressive models with exogenous variable (ARX)

$$y_t = \beta_0 + \beta_1 y_{t-1} + \dots + \beta_p y_{t-p} + \gamma_1 x_t + \dots + \gamma_q x_{t-q+1} + u_t,$$

where (x_t) is past and contemporary exogenous.

Beat OLS in Efficiency

- OLS is consistent, but is not efficient in general.
- u_t may be serially correlated and/or heteroscedastic. In such cases, GLS would be a better alternative.
- A simple way to account for serial correlation is to explicitly model ut as an ARMA process:

$$y_t = x'\beta + u_t,$$

where $u_t \sim ARMA(p,q)$. But OLS is no longer able to estimate this model. Instead, nonlinear least square or MLE should be used.

Granger Causality

- Granger causality means that if x causes y, the x is a useful predictor of y_t.
- Granger Causality Test. In the model

$$y_t = \beta_0 + \beta_1 y_{t-1} + \dots + \beta_p y_{t-p} + \gamma_1 x_{t-1} + \dots + \gamma_q x_{t-q} + u_t.$$

We test:

$$\mathrm{H}_{\mathbf{0}}: \gamma_{\mathbf{1}} = \cdots = \gamma_{\mathbf{q}} = \mathbf{0}.$$

- The above test should be more appropriately called a non-causality test. Or even more precisely, a non-predicting test.
- Example: Monetary cause of inflation.

$$\pi_t = \beta_0 + \beta_1 \pi_{t-1} + \dots + \beta_p \pi_{t-p} + \gamma_1 M \mathbf{1}_{t-1} + \dots + \gamma_q M \mathbf{1}_{t-q} + u_t.$$